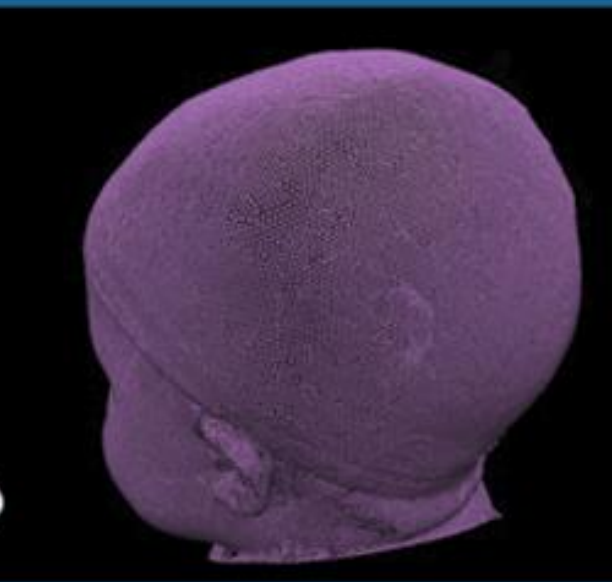


3D Face Hallucination from a Single Depth Frame

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University of Washington

Goal

- Given:
 - A single RGBD frame
- Produce:
 - High-res and personalized 3D mesh of the input





A Single frame from Kinect



Related Work

OURS:

- Single depth frame
- Personalized result
- Metrically correct

RELATED:

- KinectFusion
[Newcombe et al. 2011]
 - Requires several frames
 - Non-moving
- Morphable model
[Blanz et al. 1999][Weise et al. 2011][Cao et al. 2013]
 - Limited by a linear span of faces
- Shape from Shading
[Kemelmacher-Shlizerman et al. 2011]
 - prone to gauge and bas-relief ambiguities

Method



A single Kinect Frame



1204

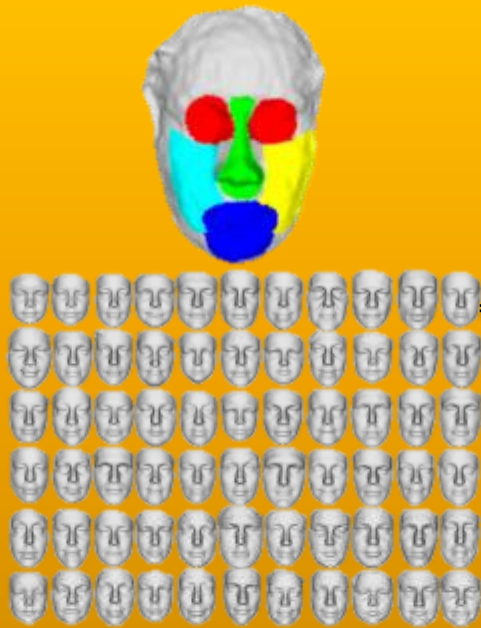
Pipeline



Raw Kinect Input
Single RGBD + 83
fiducials

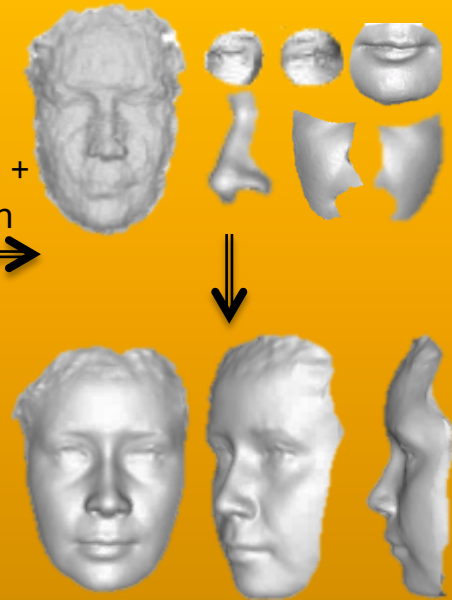
Aligning a Single Depth
Frame

Nonrigid
registration



Part-based Matching

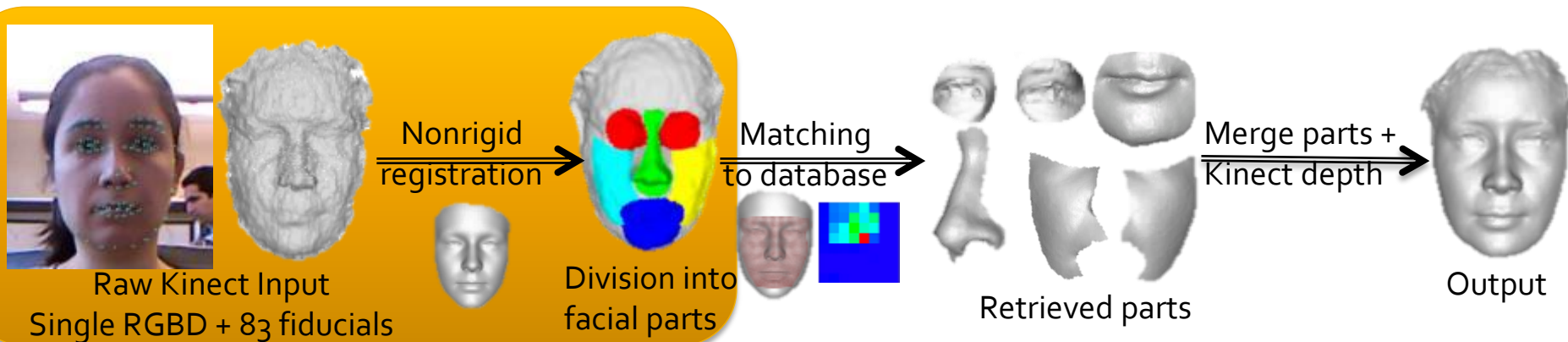
Merge parts +
Kinect depth



Merging

Aligning the input to the database

- 83 fiducial points on RGB using Face++
- Rigid pose alignment via Procrustes analysis
- Non-rigid registration [Allen et al. 2003]
- Define five facial parts



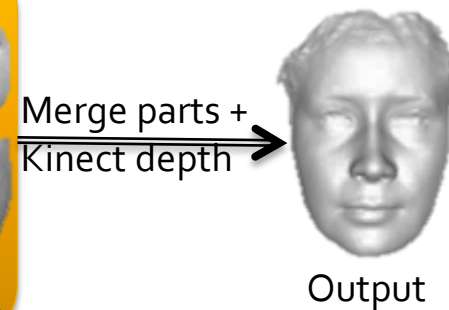
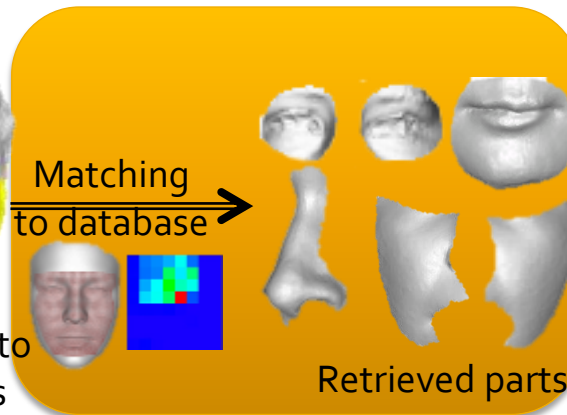
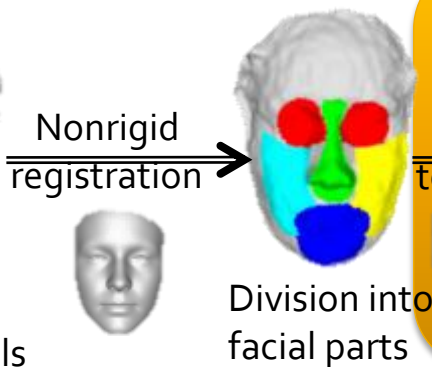
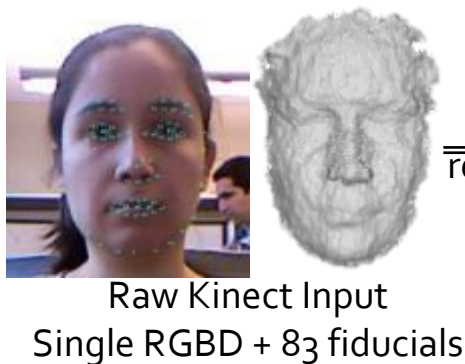
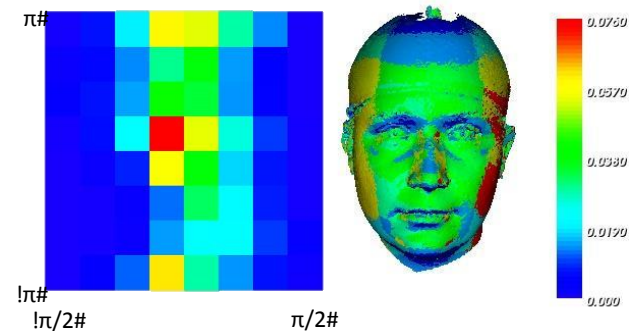
Part-based matching

- Distance function: a combination of pseudo-landmarks and a histogram of azimuth-elevation angles of normals

$$D_{pts}^j = \sum_{i=1}^{(m+2)n} \|P_i^j - P_i^{input}\|^2$$

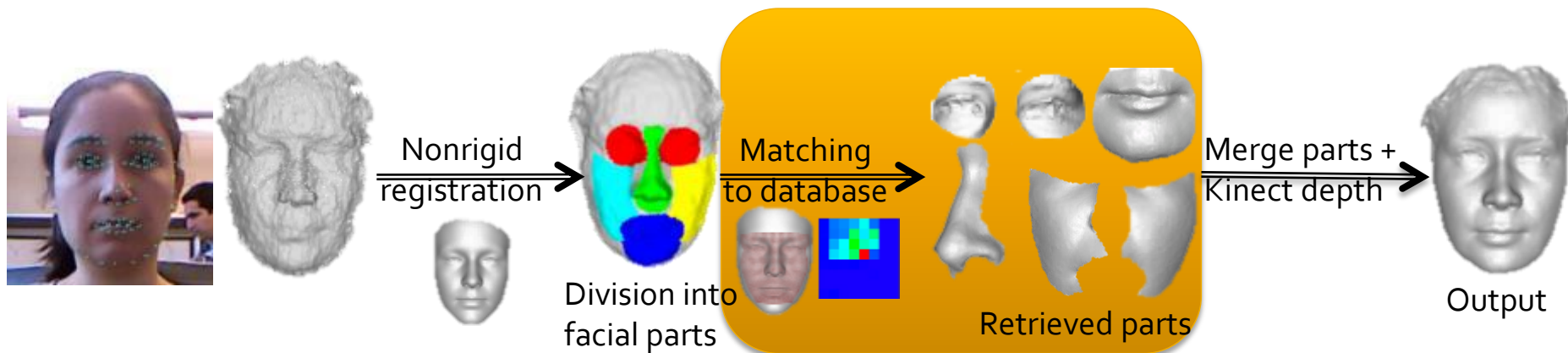
$$D_{normals} = \chi^2(H^j, H^{input})$$

$$D = D_{pts} + \alpha D_{normals}$$



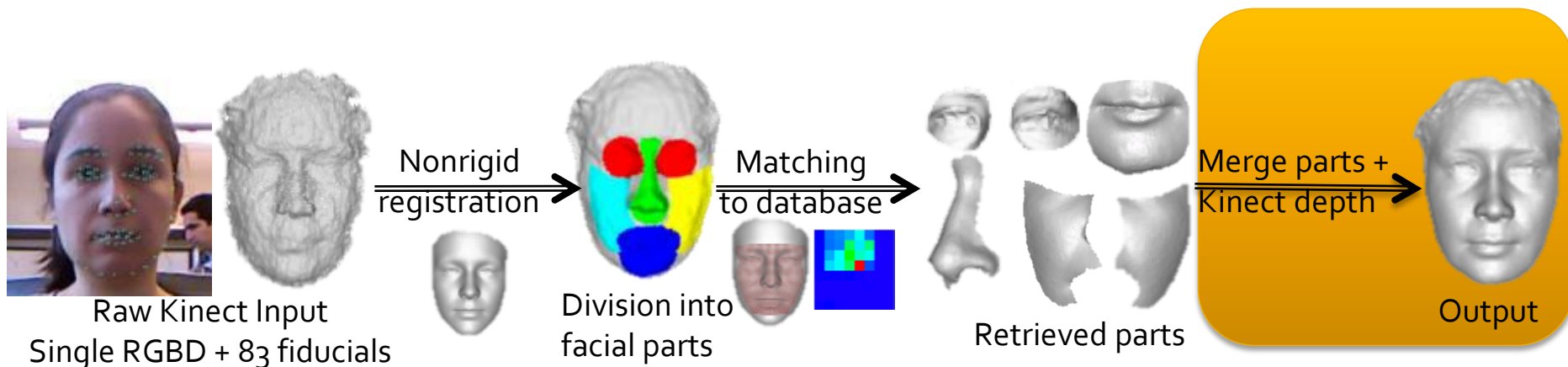
Part-based matching

- Distance function: a combination of pseudo-landmarks and a histogram of azimuth-elevation angles of normals
- Weights chosen according to our similarity evaluation of 7 subjects

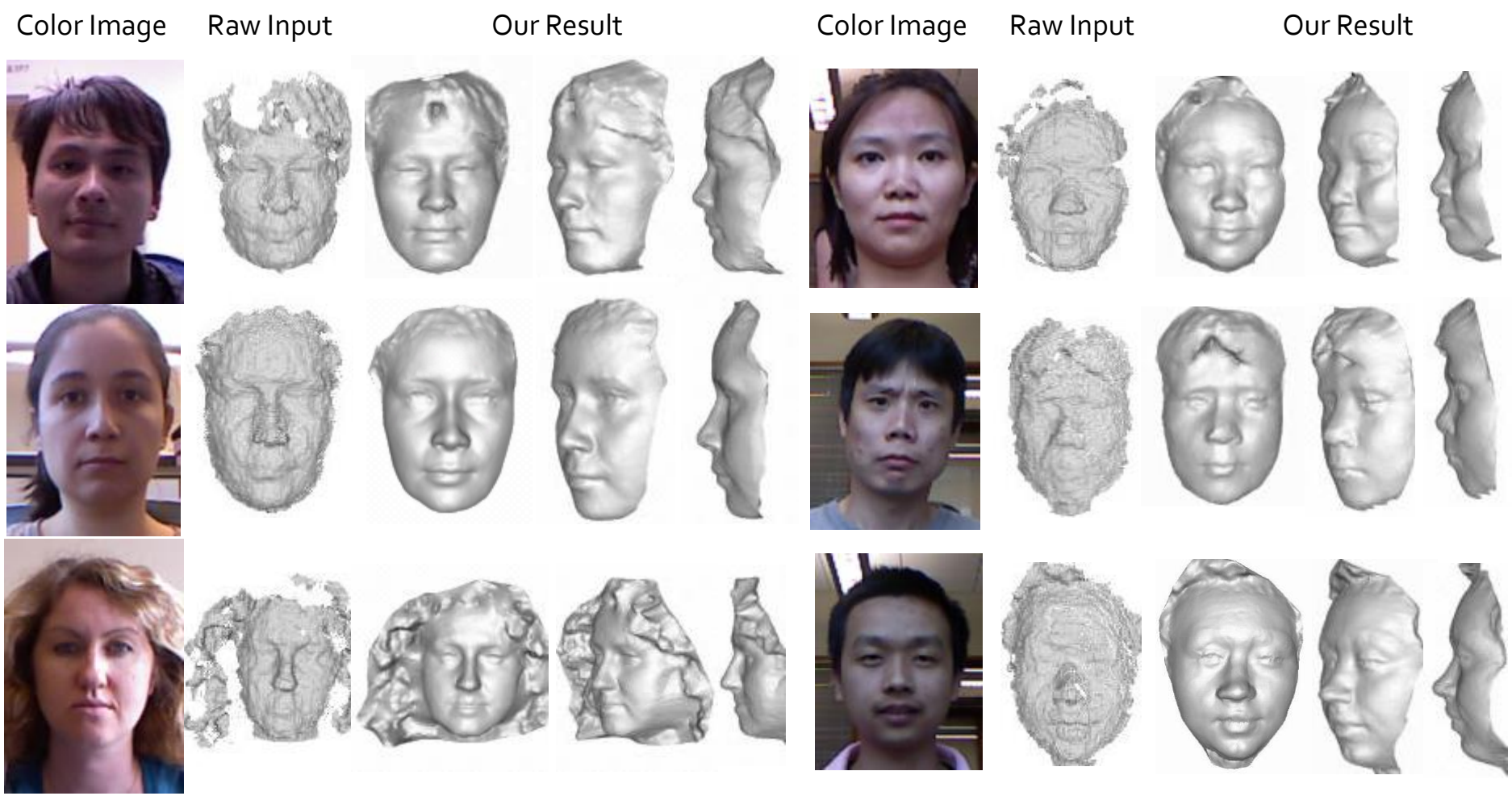


Merging the matches

- Skin region: vertex normal transferred from matched shapes. Hair region: original normal kept
- Combining depth and normal [Nehab et al. 2005]
- Faces with expression: one neutral frame for retrieval, one expression frame for merging

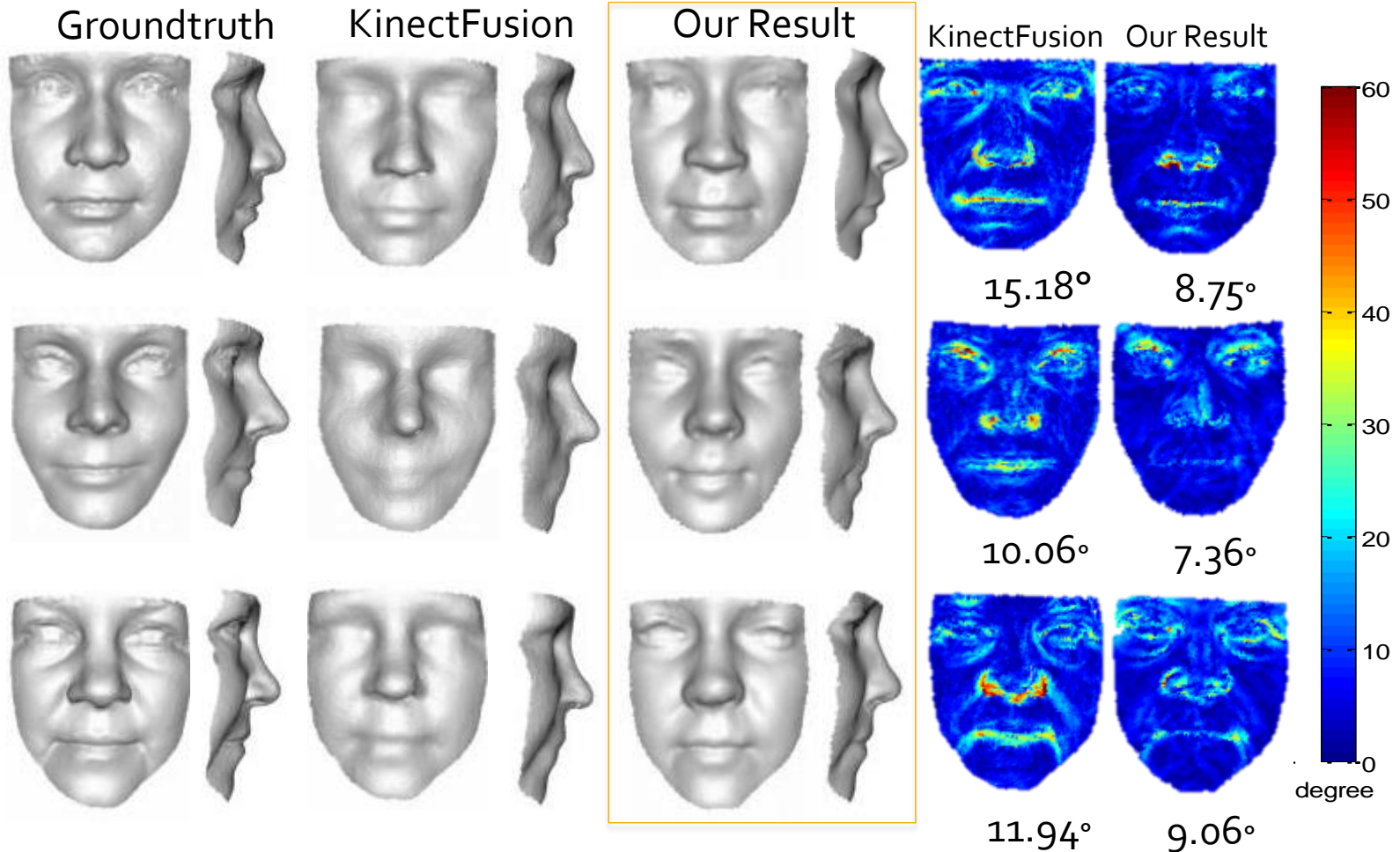


Results for neutral faces



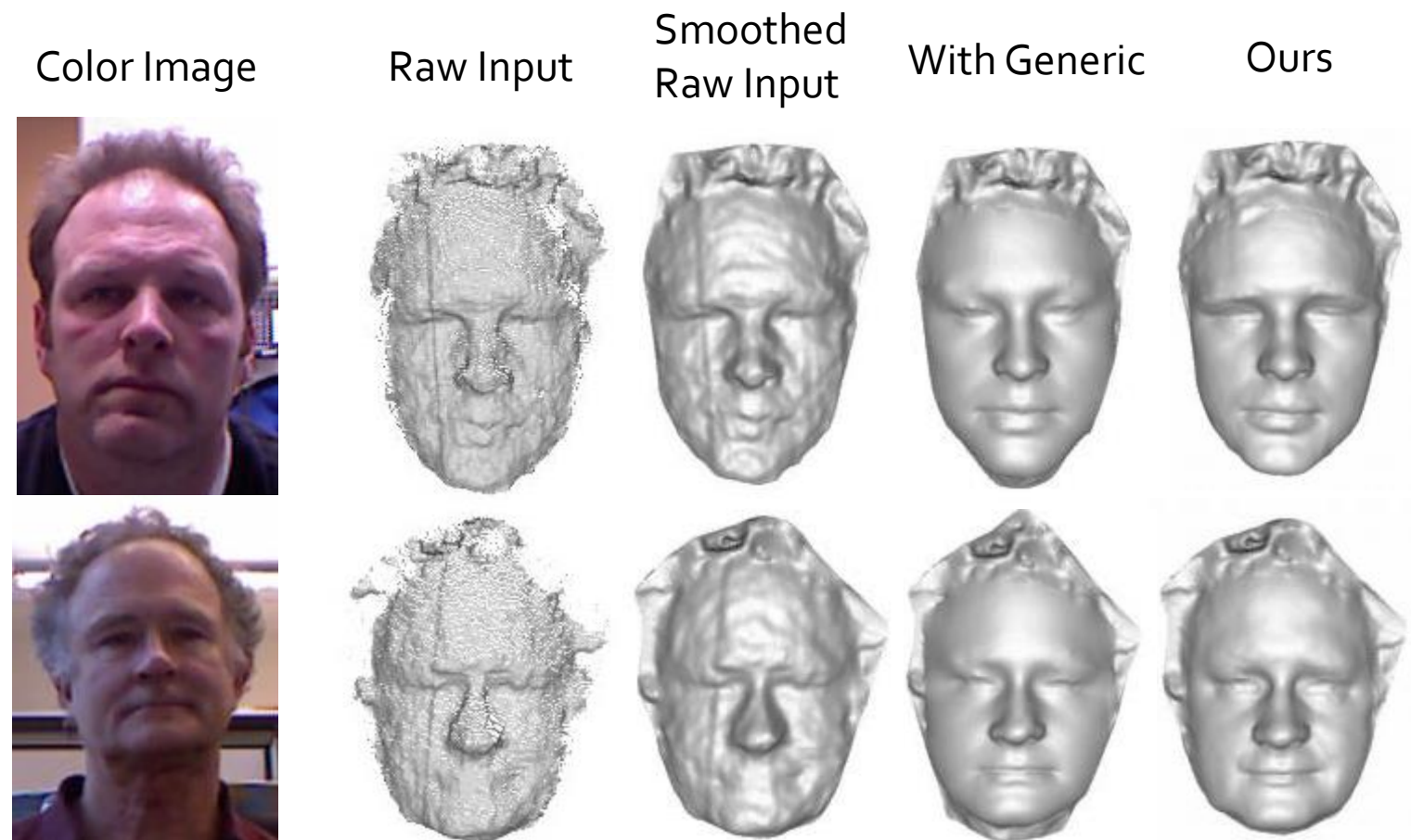
Comparison

- With KinectFusion(Kinect for Windows SDK 1.8)



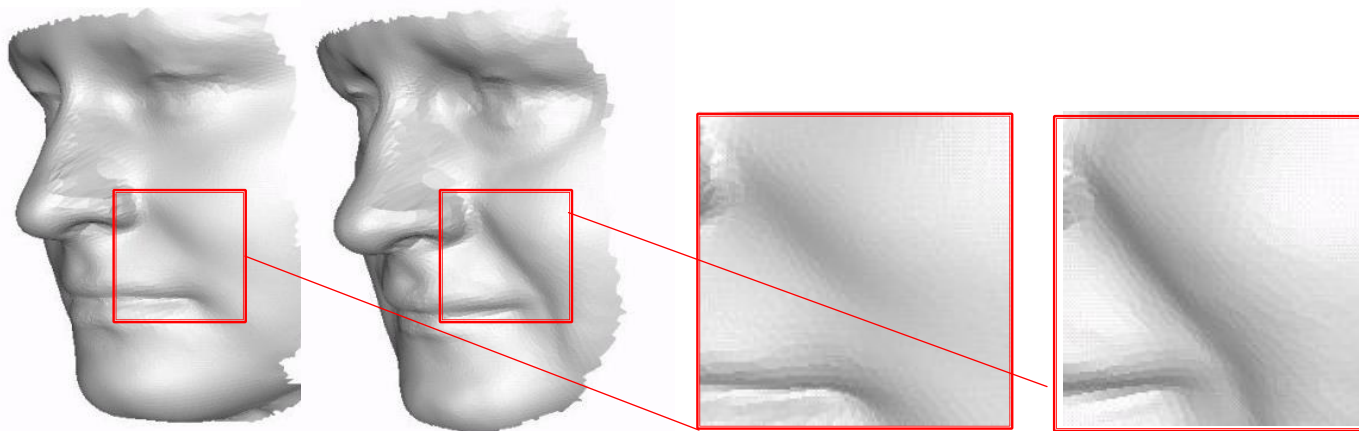
Comparison

- With details from a generic shape



Comparison

- With details from a generic shape



a) Details from the generic shape

b) Details from similar facial components

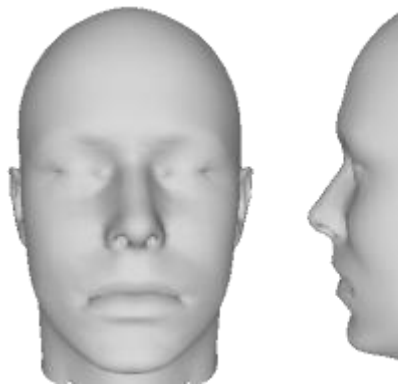
Comparison

- With Morphable Model method(Vizago)

Color Image



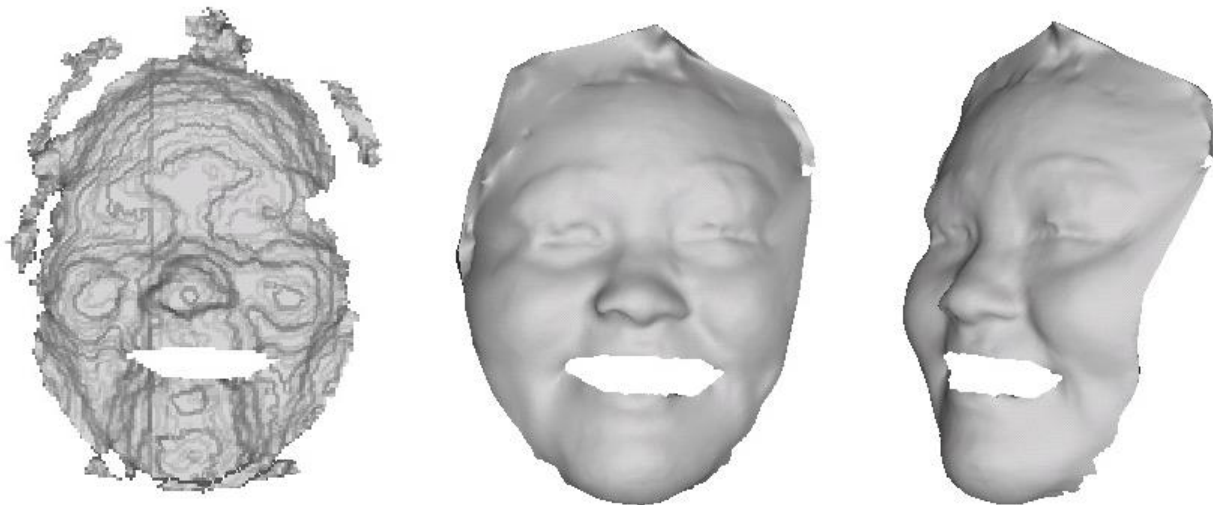
Morphable Model



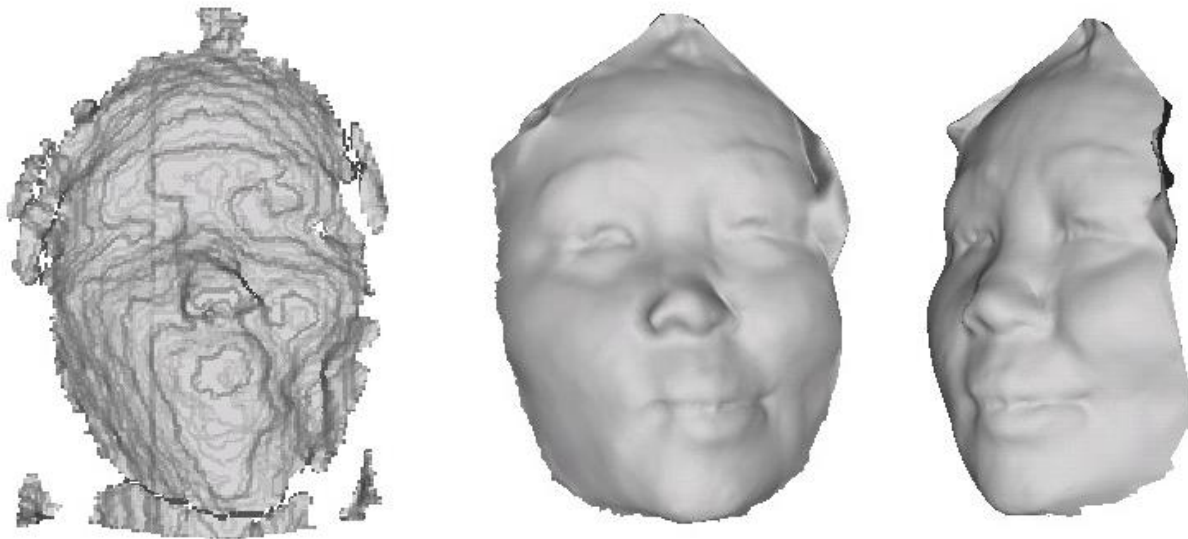
Our Result



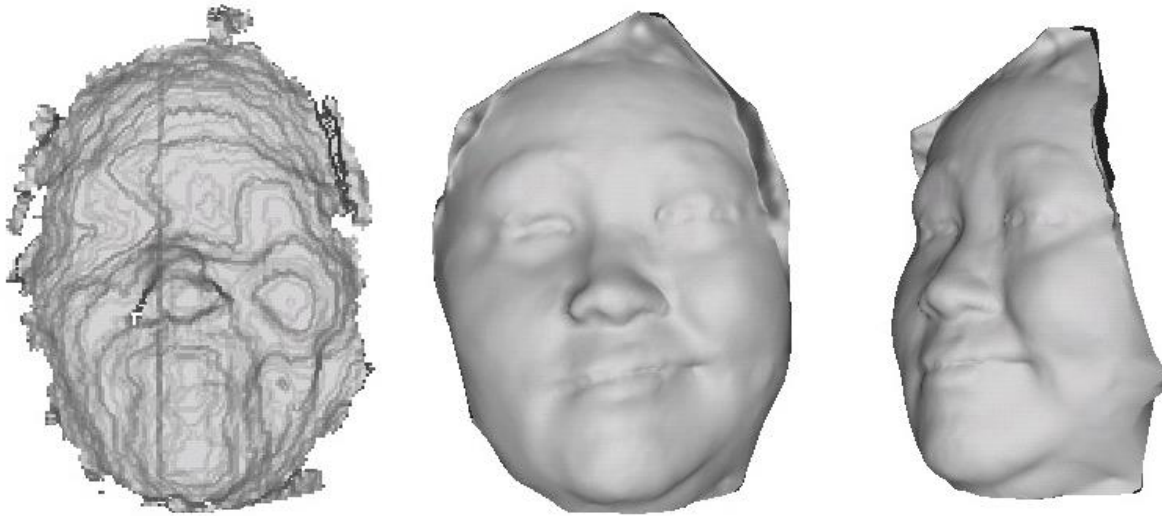
Expression results



Expression results



Expression results



Expression results

